# THE DETECTOR MENAGERIE

A COLLECTION OF DROP-IN DYNAMIC COMPONENTS FOR MODELING THE ELECTRON-ION COLLIDER

## CENTRAL DETECTOR COMPONENTS



## **IP-6 Fixed Carriage**

### Overview

The *IP-6 fixed carriage model* is a proposed design that makes several assumptions. First, it assumes that the STAR cradles will be reused and will be fitted with *inserts* that allow them to accommodate a variety of HCAL radii. Adjustable carriage jacks are included in this model to simulate the supports that may need to be added to accommodate different HCALs.

A second assumption is that the supporting infrastructure for the detector will be installed on a service carriage. While this is expected to reduce the length of service/communications lines, it also allows the detector to be moved in and out of the collider hall, while disturbing a minimum number of connections.

### **Component Options**

| Х                       | Position of the object's origin relative to the red axis (horizontal axis orthogonal to the beamline).                 |
|-------------------------|--|
| Υ                       | Position of the object's origin relative to the green axis (horizontal axis parallel to the beamline).                 |
| Z                       | Position of the object's origin relative to the blue axis (vertical axis orthogonal to the beamline).                  |
| Carriage Jack<br>Length | Length of the carriage jacks. This parameter allows the jack length to be adjusted to support a variety of HCAL radii. |

All component dimensions are specified as centimeters unless otherwise stated.

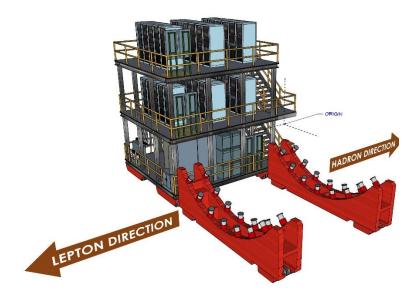


Figure 1: IP-6 Fixed Carriage

## **Methods for Weight Estimation**

The total weight of this carriage design can be estimated using a parametric approach. The following volumes and material weights may be adapted for use.

| Item                 | Basis              | Weight        |
|----------------------|--------------------|---------------|
| Carriage (5.9 m³)    | Steel (7850 kg/m³) | 46,451.91 kg  |
| Cradles (2@3.44 m³)  | Steel (7850 kg/m³) | 54,044.96 kg  |
| Power Supplies (2)   | 850.03 kg each     | 1,700.06 kg   |
| Computing Racks (39) | 226.80 kg each     | 8,845.04 kg   |
| Transformers (4)     | 231.33 kg each     | 925.33 kg     |
|                      | Total              | 111,967.31 kg |

This is a preliminary list for planning purposes only. As new components are added to the service carriage, their weights should be included in the table.



## **IP-8 Fixed Carriage**

#### Overview

The *IP-8 fixed carriage model* is derived from the sPHENIX carriage. The user should note that the proposed placement of this carriage will result in an interference between the carriage and the door when the detector is moved from the detector hall to the assembly area. Actual use of this carriage will require some modification.

Unlike the IP-6 carriage, the door between the detector hall and assembly hall is sufficiently high that the electronics and supporting infrastructure can be installed above the detector. This results in a more compact design, but does limit the amount of equipment that may be installed. Other alternative designs consider adding a service carriage toward the interior of the detector hall, but this may have other implications – particularly if a turntable is used to rotate the carriage.

## **Component Options**

| Х | Position of the object's origin relative to the red axis (horizontal axis orthogonal to the beamline). |
|---|--|
| Υ | Position of the object's origin relative to the green axis (horizontal axis parallel to the beamline). |
| Z | Position of the object's origin relative to the blue axis (vertical axis orthogonal to the beamline).  |

All component dimensions are specified as centimeters unless otherwise stated.

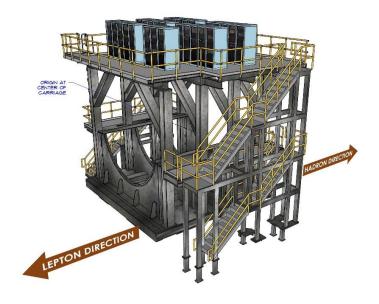


Figure 2: IP-8 Fixed Carriage

## **Methods for Weight Estimation**

Jonathan Hock of Brookhaven National Lab estimates the total weight of this carriage to be 110 tons or 99,790 kg. This weight includes the four cradles and the base. The following table of values may be used to compute weight changes based on alternations in what is installed.

| Item            | Basis          |
|-----------------|----------------|
| Power Supplies  | 850.03 kg each |
| Computing Racks | 226.80 kg each |
| Transformers    | 231.33 kg each |

As new components (and component types) are added to the service carriage, their weights should be included in the table.



## **Barrel Hadron Calorimeter (1 Part)**

#### Overview

The barrel hadron calorimeter is the outer most detector and its radius governs the maximum radius of the central detector. For this collection of models, there are currently three types of HCALs. They have one, two and three part barrels respectively, along the radius to vary along the length of the detector. This component has a one part barrel, meaning that it has a continuous bore radius across its entire length.

In the interest of consistency, this component is constructed from 24 radial segments. As a central detector, its origin is located in the exact center of the object and its *offset* parameter can be used to move it along the beamline.

### **Component Options**

The barrel hadron calorimeter has the following options.

| -                     |  |
|-----------------------|--|
| X, Y, Z               | Position of the object's origin relative to the red, green and blue axes respectively.   |
| Detector<br>Length    | Total length of the detector along the beam line.  |
| Bore                  | Radius from the origin to the inside of the detector.  |
| Radius                | Radius from the origin to the outside of the detector.   |
| Offset from<br>Center | Distance along the beamline that the detector's origin is offset from the interaction point. (HD is negative and LD is positive) |
| Volume                | Volume in cubic meters of the detector (read-<br>only, computed as cylinders).   |

All component dimensions are specified as centimeters unless otherwise stated.

### **Methods for Weight Estimation**

One method of weight estimation for the barrel hadron calorimeter has been developed using the specifications from the CMS Hadron Calorimeter at CERN. The CMS HB HCAL is constructed from brass

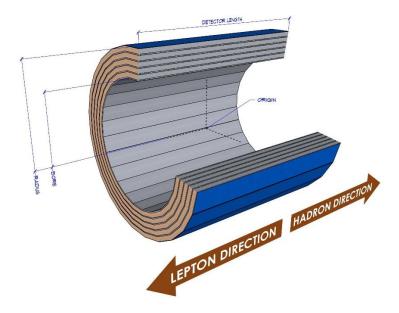


Figure 3: Barrel Hadron Calorimeter ( 1 Part )

and plastic scintillator (CERN, Detector | CMS Experiment, 2021), and consist of 36 segments weighing 26 tons each, totaling 936 tons (849,125 kg) (CERN, 2021). The HB HCAL has a total volume of 109.5732 cubic meters (Abdullin, 2007).

Using the densities of brass (8,730 kg/m³) and scintillator plastics (1,023 kg/m³) in conjunction with the other parameters, it can be determined that this hadron calorimeter consist of 87.2763% brass and 12.7237% plastic. Instead of brass, this project will be using iron for the hadron calorimeter which has a density of 7,874 kg/m³.

Therefore, the following formula can be used to estimate the weight of a similarly constructed hadron calorimeter with a volume given in m<sup>3</sup>.

weight = (0.872763\*7874+0.127237\*1023)\*volume weight = 7002.3 \* volume



## **Barrel Hadron Calorimeter (2 Part)**

#### Overview

This is a two-part barrel hadron calorimeter. The component consists of a lepton direction and hadron direction section, each of which have independently configurable radii.

As with other central detector components, the origin is in the center of the object and its position along the beamline is adjusted using the offset parameter. Positive offset values move the component in the lepton direction, while negative values move the component in the hadron direction.

In order to be consistent with the other components in the collection, this object is constructed using 24 radial segments. For simplicity, though, the volume of the component is computed using cylindrical volumes, which should be adequate for estimating weights.

## **Component Options**

The following options are available for configuring this component.

| X, Y, Z    | Position of the object's origin relative to the red, green and blue axes respectively. |
|------------|--|
| Detector   | Total length of the detector along the beam  |
| Length     | line (read-only).  |
| LD Section | Length of the lepton direction section.  |
| Len        |  |
| HD Section | Length of the hadron direction section.  |
| Len        |  |
| LD Bore    | Radius from the origin to the inside of the  |
| Radius     | lepton direction section of the detector.  |
| HD Bore    | Radius from the origin to the inside of the  |
| Radius     | hadron direction section of the detector.  |
| Radius     | Radius from the origin to the outside of the   |
|            | detector.  |

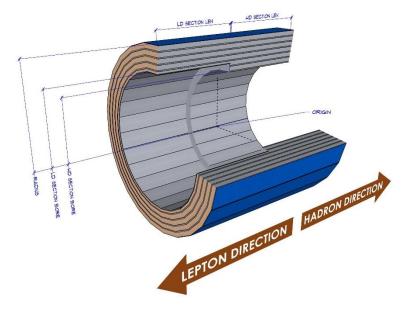


Figure 4: Barrel Hadron Calorimeter ( 2 Part )

| Offset from<br>Center | Distance along the beamline that the detector's origin is offset from the interaction point. (HD is negative and LD is positive) |
|-----------------------|--|
| Volume                | Volume in cubic meters of the detector (read-<br>only, computed as cylinders).   |

All component dimensions are specified as centimeters unless otherwise stated.

### **Methods for Weight Estimation**

Weight estimates for this object are also based on the CMS HB Hadron Calorimeter as described earlier. Using this approach, the weight can be calculated by applying a coefficient to the volume measured in m<sup>3</sup>, where:

weight = volume \* 7002.3

where volume is given in cubic meters and the density is provided as  $kg/m^3$ .

See the section describing the **one-part barrel hadron calorimeter** for details.



## **Barrel Hadron Calorimeter (3 Part)**

#### Overview

This is a three-part barrel hadron calorimeter. The component consists of a lepton direction, center and hadron direction section, each of which have independently configurable radii.

As with other central detector components, the origin is in the center of the object and its position along the beamline is adjusted using the offset parameter. Positive offset values move the component in the lepton direction, while negative values move the component in the hadron direction.

In order to be consistent with the other components in the collection, this object is constructed using 24 radial segments. For simplicity, though, the volume of the component is computed using cylindrical volumes, which should be adequate for estimating weights.

## **Component Options**

The following options are available for configuring this component.

| X, Y, Z               | Position of the object's origin relative to the red, green and blue axes respectively. |
|-----------------------|--|
| Detector<br>Length    | Total length of the detector along the beam line (read-only).                          |
| LD Section<br>Len     | Length of the lepton direction section.  |
| Center<br>Section Len | Length of the center section.  |
| HD Section<br>Len     | Length of the hadron direction section.  |
| LD Bore<br>Radius     | Radius from the origin to the inside of the lepton direction section.                  |
| Center Bore<br>Radius | Radius from the origin to the inside of the center section.                            |
| HD Bore<br>Radius     | Radius from the origin to the inside of the hadron direction section.                  |
| Radius                | Radius from the origin to the outside of the detector.                                 |

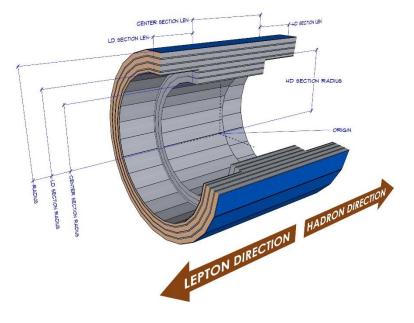


Figure 5: Barrel Hadron Calorimeter ( 3 Part )

| Offset from<br>Center | Distance along the beamline that the detector's origin is offset from the interaction point. (HD is negative and LD is positive) |
|-----------------------|--|
| Volume                | Volume in cubic meters of the detector (read-<br>only, computed as cylinders).   |

All component dimensions are specified as centimeters unless otherwise stated.

### **Methods for Weight Estimation**

Weight estimates for this object are also based on the CMS HB Hadron Calorimeter as described earlier. Using this approach, the weight can be calculated by applying a coefficient to the volume measured in m<sup>3</sup>, where:

weight = volume \* 7002.3

where volume is given in cubic meters and the density is provided as  $kg/m^3$ .

See the section describing the **one-part barrel hadron calorimeter** for details.



## **Solenoid Cryostat**

#### Overview

This component represents the cryostat for the solenoid magnet within the detector. It has a configurable length, radius and bore. The origin of this object is at its center, and its position along the beamline is adjusted using the offset parameter.

Because the objects in this collection are simplified to make them lightweight and easy to use, this cryostat does not show the connections that lead to the cryogenic system. Still, the final design will need to consider the entry point for cryogenic services and how they will be routed through the rest of the system.

## **Component Options**

The following options are available for configuring this component.

| X, Y, Z               | Position of the object's origin relative to the red, green and blue axes respectively.   |
|-----------------------|--|
| Cryostat<br>Length    | Total length of the cryostat along the beam line.  |
| Bore                  | Radius from the origin to the inside of the cryostat.  |
| Radius                | Radius from the origin to the outside of the cryostat.   |
| Offset from<br>Center | Distance along the beamline that the cryostat's origin is offset from the interaction point. (HD is negative and LD is positive) |
| Volume                | Volume in cubic meters of the detector (read-<br>only, computed as cylinders).   |

All component dimensions are specified as centimeters unless otherwise stated.

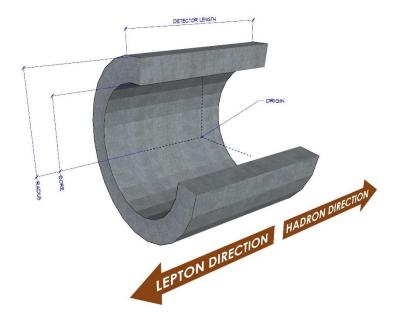


Figure 6: Solenoid Cryostat

## **Methods for Weight Estimation**

The weight of this component may be computed using the known weight and volume of the CLEO II cryostat as a parametric basis. The CLEO II cryostat has a total weight of 22,000 kg and a volume of 11.3021 cubic meters (Kubota, 1992). Therefore, the weight of any similar cryostat can be estimated using a coefficient in conjunction with the volume measured in m³, where:



## **Barrel Support**

#### Overview

The barrel support component is a simplification of the barrel calorimeter support design developed by Roland Wimmer at Brookhaven National Laboratory. The role of this component is to support the barrel electromagnetic calorimeter within the solenoid cryostat. It has extension arms that transfer the weight of it and its contents to the bore of the barrel hadron calorimeter.

The supporting walls of this component are 7.62 cm thick, therefore that space must be included between the bore of the cryostat and the exterior radius of the barrel electromagnetic calorimeter. This object will be constructed from non-magnetic stainless steel.

### **Component Options**

The following options are available for configuring the barrel support.

| -                     |  |
|-----------------------|--|
| X, Y, Z               | Position of the object's origin relative to the red, green and blue axes respectively.   |
| Structure<br>Length   | Total length of the structure along the beam line.   |
| Bore                  | The radius from the origin to the inside of the structure.   |
| Radius                | The radius from the origin to the outside of the structure (should be equal to the bore of the parent detector).                     |
| Support<br>Radius     | The radius from the origin to the supporting structure to which this assembly attaches.  |
| Offset from<br>Center | The distance along the beamline that the detector's origin is offset from the interaction point. (HD is negative and LD is positive) |

All component dimensions are specified as centimeters unless otherwise stated.

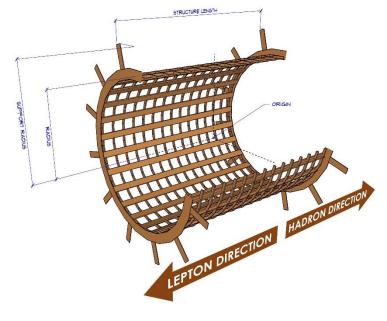


Figure 7: Barrel Support

## **Methods for Weight Estimation**

Because the barrel support will be custom built based on the dimensions of surrounding objects, it is difficult to provide an exact method for computing the weight without constructing a CAD model. However, using a density of 7,480 kg/m³ for stainless steel, it is possible to produce a rough estimate based on the radius and length of the barrel support in current models.

The formula for producing this rough weight estimate is:

weight = PI \* radius
$$^2$$
 \* length \* 157.6 kg

Therefore, a barrel support with a radius of 1.60 m and a length of 3.84 m can be estimated to weigh 4,867 kg.



## **Inhomogeneous Barrel Electromagnetic Calorimeter**

#### Overview

The inhomogeneous barrel electromagnetic calorimeter is another of the central detector components. Its general dimensions are specified by providing a detector length, radius and bore. The origin of this component is at the center, and its position along the beamline is altered by changing the offset parameter.

This object is constructed from 24 radial segment like many of the other components in the collection. For simplicity, the volume is computed by subtracting the cylindrical volume of the bore from the cylindrical volume of the radius.

The "inhomogeneous" barrel electromagnetic calorimeter has crystals that run the length of the detector.

## **Component Options**

The following options are available for configuring this component.

| X, Y, Z               | Position of the object's origin relative to the red, green and blue axes respectively.   |
|-----------------------|--|
| Detector<br>Length    | Total length of the detector along the beam line.  |
| Bore                  | Radius from the origin to the inside of the detector.  |
| Radius                | Radius from the origin to the outside of the detector.   |
| Offset from<br>Center | Distance along the beamline that the detector's origin is offset from the interaction point. (HD is negative and LD is positive) |
| Volume                | Volume in cubic meters of the detector (read-<br>only, computed as cylinders).   |

All component dimensions are specified as centimeters unless otherwise stated.

## **Methods for Weight Estimation**

Weight estimates for the barrel electromagnetic calorimeter are dependent on the technology and the construction material. For this document, the CMS electromagnetic calorimeter was used to create a parametric estimate. The cylindrical barrel of the CMS ECAL-EB detector consists of 61,200 crystals

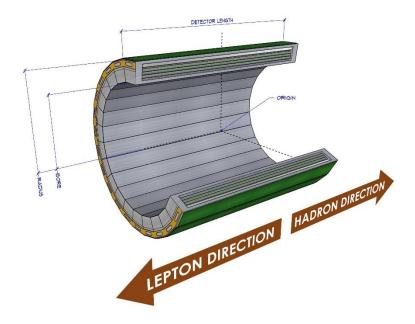


Figure 8: Inhomogeneous Barrel Electromagnetic Calorimeter

formed into 36 "supermodules", each weighing around three tons and containing 1700 crystals, for a total weight of 97,976 kg (CERN, 2021). Based on reference documents, the volume of the ECAL-EB is 27.94 m<sup>3</sup> (Abdullin, 2007).

Further, the ECAL-EB is constructed of 61,200 lead tungstate crystals measuring 2.2cm x 2.2cm x 23cm with a density of 8.3 g/cm³ (CERN, 2021). Therefore, 58% of the weight of this detector is represented by lead tungstate glass, while 42% of the detector is represented by other materials. Using this information, a general, volume-based estimate for the weight of the barrel calorimeter is given by:

weight = volume \* 3,506.66

where volume is the total volume of the barrel calorimeter given in cubic meters.

If crystals will be used with a different density, then the weight can be estimated as:

weight = density\*volume\*0.2438 + volume\*1482.82

where density is the density of the crystals given in kg/m³ and volume is the total volume of the barrel calorimeter given in cubic meters.



## **Homogeneous Barrel Electromagnetic Calorimeter**

#### Overview

The homogeneous barrel electromagnetic calorimeter is another of the central detector components. Its general dimensions are specified by providing a detector length, radius and bore. The origin of this component is at the center, and its position along the beamline is altered by changing the offset parameter.

This object is constructed from 24 radial segment like many of the other components in the collection. For simplicity, the volume is computed by subtracting the cylindrical volume of the bore from the cylindrical volume of the radius.

The "homogeneous" barrel electromagnetic calorimeter has crystals that are positioned orthogonal to the beamline.

## **Component Options**

The following options are available for configuring this component.

| X, Y, Z               | Position of the object's origin relative to the red, green and blue axes respectively.   |
|-----------------------|--|
| Detector<br>Length    | Total length of the detector along the beam line.  |
| Bore                  | Radius from the origin to the inside of the detector.  |
| Radius                | Radius from the origin to the outside of the detector.   |
| Offset from<br>Center | Distance along the beamline that the detector's origin is offset from the interaction point. (HD is negative and LD is positive) |
| Volume                | Volume in cubic meters of the detector (read-<br>only, computed as cylinders).   |

All component dimensions are specified as centimeters unless otherwise stated.

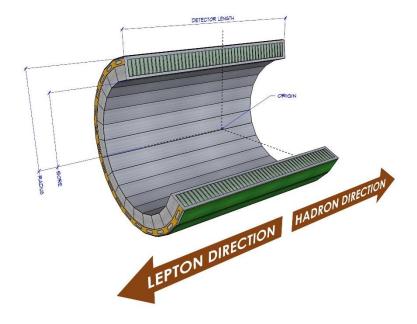


Figure 9: Homogeneous Barrel Electromagnetic Calorimeter

## **Methods for Weight Estimation**

Weight estimates for the barrel electromagnetic calorimeter are based on the CMS electromagnetic calorimeter described earlier. Using this approach, a general, volume-based estimate for the weight of the barrel calorimeter is given by:

weight = volume \* 3,506.66 where volume is the total volume of the barrel calorimeter given in cubic meters.

If crystals will be used with a different density, then the weight can be estimated as:

weight = density\*volume\*0.2438 + volume\*1482.82

where density is the density of the crystals given in kg/m³ and volume is the total volume of the barrel calorimeter given in cubic meters.



## Homogeneous-Projective Barrel Electromagnetic Calorimeter

#### Overview

The homogeneous-projective barrel electromagnetic calorimeter is another of the central detector components. Its general dimensions are specified by providing a detector length, radius and bore. The origin of this component is at the center, and its position along the beamline is altered by changing the offset parameter.

This object is constructed from 24 radial segment like many of the other components in the collection. For simplicity, the volume is computed by subtracting the cylindrical volume of the bore from the cylindrical volume of the radius.

The "homogeneous-projective" barrel electromagnetic calorimeter has crystals that are positioned radially to the interaction point.

## **Component Options**

The following options are available for configuring this component.

| X, Y, Z               | Position of the object's origin relative to the red, green and blue axes respectively.   |
|-----------------------|--|
| Detector<br>Length    | Total length of the detector along the beam line.  |
| Bore                  | Radius from the origin to the inside of the detector.  |
| Radius                | Radius from the origin to the outside of the detector.   |
| Offset from<br>Center | Distance along the beamline that the detector's origin is offset from the interaction point. (HD is negative and LD is positive) |
| Volume                | Volume in cubic meters of the detector (read-<br>only, computed as cylinders).   |

All component dimensions are specified as centimeters unless otherwise stated.

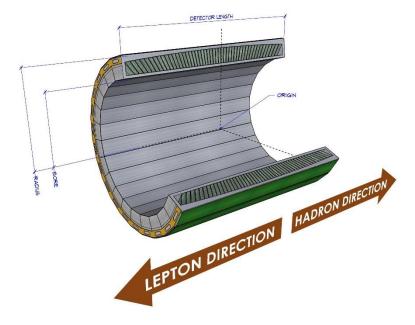


Figure 10: Homogeneous-Projective Barrel Electromagnetic Calorimeter

### **Methods for Weight Estimation**

Weight estimates for the barrel electromagnetic calorimeter are based on the CMS electromagnetic calorimeter described earlier. Using this approach, a general, volume-based estimate for the weight of the barrel calorimeter is given by:

weight = volume \* 3,506.66

where volume is the total volume of the barrel calorimeter given in cubic meters.

If crystals will be used with a different density, then the weight can be estimated as:

weight = density\*volume\*0.2438 + volume\*1482.82

where density is the density of the crystals given in  $kg/m^3$  and volume is the total volume of the barrel calorimeter given in cubic meters.



## **AC-Coupled Low-Gas Avalanche Detector**

#### Overview

The AC-coupled low-gas avalanche detector homogeneous (AC-LGAD) is a proposed component of the central detector. Because this is a new configuration for this type of detector, most of the modeling information contained here is speculative, as is the physical design of the component. Like the other detectors, its general dimensions are specified by providing a detector length, radius and bore. The origin of this component is at the center, and its position along the beamline is altered by changing the offset parameter.

This object is constructed from 24 radial segment like many of the other components in the collection. For simplicity, the volume is computed by subtracting the cylindrical volume of the bore from the cylindrical volume of the radius.

### **Component Options**

The following options are available for configuring this component.

| X, Y, Z               | Position of the object's origin relative to the red, green and blue axes respectively.   |
|-----------------------|--|
| Detector<br>Length    | Total length of the detector along the beam line.  |
| Bore                  | Radius from the origin to the inside of the detector.  |
| Radius                | Radius from the origin to the outside of the detector.   |
| Offset from<br>Center | Distance along the beamline that the detector's origin is offset from the interaction point. (HD is negative and LD is positive) |
| Volume                | Volume in cubic meters of the detector (read-<br>only, computed as cylinders).   |

All component dimensions are specified as centimeters unless otherwise stated.

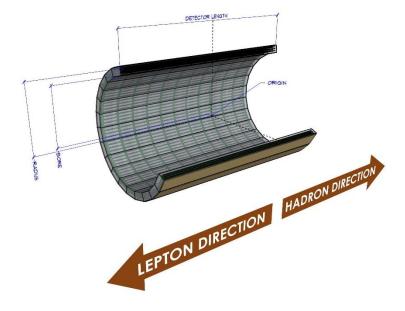


Figure 11: Barrel Electromagnetic Calorimeter

### **Methods for Weight Estimation**

Because the design of this component is speculative, the weight estimate is also somewhat vague. For the purpose of this calculation it is assumed that the device has a metallic covering (14 gauge stainless steel at 15.93 kg/m²) and the volume is filled with 50% silicon and 50% air (or gas).

covering weight =  $0.001593 * \pi * ((2 * radius * len) + (2 * bore * len) + (radius^2 - bore^2))$ silicon weight = 2330\*volume/2

where the total weight is the sum of the covering weight and the silicon weight.



## **Lepton Direction DIRC**

#### Overview

This is the first of two DIRC detector components. The supports are based on a design by Roland Wimmer. In this configuration, the DIRC's readouts are facing in the lepton direction and the DIRC bars extend toward the center in the hadron direction.

The DIRC detector differs from the other central systems in a number of ways. First, the origin of the DIRC is not in the center of the component, but rather, immediately behind the readout – where the DIRC bars begin. This allows the length of the DIRC bars to be independently configurable and the readout remains anchored in place as the bar length increases. Additionally, because the

DIRC segments are a fixed size, the number of segments increase as the radius increases, in order to maximize coverage. This means that a DIRC detector with a radius of 100 will have 15 segments, while a DIRC with a radius of 400 will have 62 segments.

The bore size is automatically computed based on the size of the support structure and the radius of the overall detector. This value is calculated within the model to make it easier to specify the size of subcomponents within the DIRC.

To simplify weight calculations, the component automatically provides estimates for the volume of the detector (the DIRC bars and readouts) and the volume of the support structure.

### **Component Options**

The following options are available for configuring this component.

| X, Y, Z      | Position of the object's origin relative to the red, green and blue axes respectively.   |
|--------------|--|
| DIRC Bar Len | Length of the quartz bars of the DIRC detector (all other elements have a fixed length). |

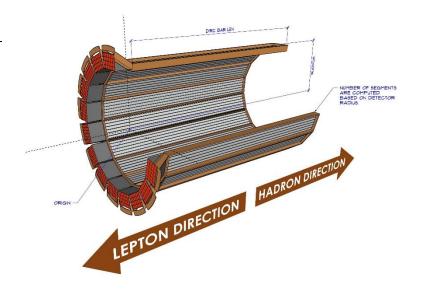


Figure 12: Lepton Direction DIRC

| Bore                  | The computed radius from the origin to the inside of the detector based on the overall radius and number of segments (read-only). |
|-----------------------|---|
| Radius                | Radius from the origin to the outside of the detector.  |
| Offset from<br>Center | Distance along the beamline that the detector's origin is offset from the interaction point. (HD is negative and LD is positive)  |
| Segment Cnt           | The number of fixed-size DIRC assemblies that can be installed in the specified radius.   |
| Detector<br>Volume    | Volume in cubic meters of the detector bars and readouts (read-only).   |
| Support<br>Volume     | Volume in cubic meters of the support structure (read-only).  |

All component dimensions are specified as centimeters unless otherwise stated.

## **Methods for Weight Estimation**

The weight of the detector may be estimated by summing the detector volume multiplied by the density of its primary material (quartz =  $2,320 \, kg/m^3$ ) and the support volume multiplied by the density of its primary material (stainless steel =  $7,480 \, kg/m^3$ ).

weight = detector volume \* 2320 + support volume \*
7480

where volumes are given in cubic meters and densities are provided as  $kg/m^3$ .



### **Hadron Direction DIRC**

#### Overview

This is the second of the DIRC detector components. In this configuration, the DIRC's readouts are facing in the hadron direction and the DIRC bars extend toward the center in the lepton direction.

As before, the origin of the DIRC is not in the center of the component, but rather, immediately behind the readout – where the DIRC bars begin. This allows the length of the DIRC bars to be independently configurable and the readout remains anchored in place as the bar length increases. Additionally, because the DIRC segments are a fixed size, the number of segments increase as the radius increases, in order to maximize coverage. This means that a DIRC detector with a radius of 100 will have 15 segments, while a DIRC with a radius of 400 will have 62 segments.

The bore size is automatically computed based on the size of the support structure and the radius of the overall detector. This value is calculated within the model to make it easier to specify the size of subcomponents within the DIRC.

To simplify weight calculations, the component automatically provides estimates for the volume of the detector (the DIRC bars and readouts) and the volume of the support structure.

### **Component Options**

The following options are available for configuring this component.

| X, Y, Z      | Position of the object's origin relative to the red, green and blue axes respectively.  |
|--------------|---|
| DIRC Bar Len | Length of the quartz bars of the DIRC detector (all other elements have a fixed length).  |
| Bore         | The computed radius from the origin to the inside of the detector based on the overall radius and number of segments (read-only). |

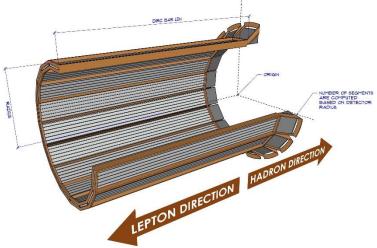


Figure 13: Hadron Direction DIRC

| Radius                | Radius from the origin to the outside of the detector.   |
|-----------------------|--|
| Offset from<br>Center | Distance along the beamline that the detector's origin is offset from the interaction point. (HD is negative and LD is positive) |
| Segment Cnt           | The number of fixed-size DIRC assemblies that can be installed in the specified radius.  |
| Detector<br>Volume    | Volume in cubic meters of the detector bars and readouts (read-only).  |
| Support<br>Volume     | Volume in cubic meters of the support structure (read-only).   |

All component dimensions are specified as centimeters unless otherwise stated.

### **Methods for Weight Estimation**

The weight of the detector may be estimated by summing the detector volume multiplied by the density of its primary material (quartz =  $2,320 \, kg/m^3$ ) and the support volume multiplied by the density of its primary material (stainless steel =  $7,480 \, kg/m^3$ ).

weight = detector volume \* 2320 + support volume \*
7480

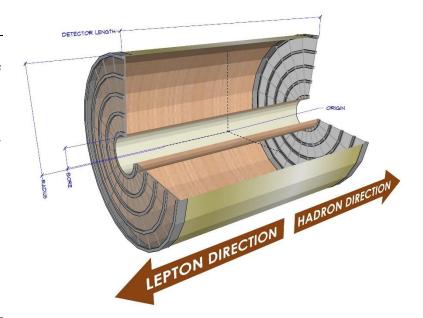
where volumes are given in cubic meters and densities are provided as  $kg/m^3$ .



## **Outer Tracking**

#### Overview

The outer tracking component is currently a placeholder that could represent a variety of tracking systems, such as a time projection chamber. As the design process continues, additional components will be introduced that better represent the exact technology being used and the options that are available.



### **Component Options**

The following options are available for configuring this component.

| X, Y, Z               | Position of the object's origin relative to the red, green and blue axes respectively.   |
|-----------------------|--|
| Detector<br>Length    | Total length of the detector along the beam line.  |
| Bore                  | Radius from the origin to the inside of the detector.  |
| Radius                | Radius from the origin to the outside of the detector.   |
| Offset from<br>Center | Distance along the beamline that the detector's origin is offset from the interaction point. (HD is negative and LD is positive) |
| Volume                | Volume in cubic meters of the detector (read-<br>only, computed as cylinders).   |

All component dimensions are specified as centimeters unless otherwise stated.

### Figure 14: Outer Tracking

## **Methods for Weight Estimation**

Because the exact technology being used for the outer tracking system has not been defined, an exact approach for estimating weight cannot be provided. Still, a preliminary estimate can be computed using the sPHENIX time project chamber as a basis.

The sPHENIX TPC is 200 cm long, with an exterior radius of 80 cm and a bore of 40 cm (Brookhaven National Laboratory, 2015), giving it a volume of 3.02 m³. This assembly has a total weight of 295.7 kg (Hemmick, 2019). Therefore, a parametric estimate for an outer tracking system using a time projection chamber is given as:

weight = volume \* 98.06



## Silicon Detector

#### Overview

The silicon detector is installed at the core of the central detector and is expected to be constructed with the inner most section of the beamline included. This is a preliminary model of the silicon detector which is based on engineering models created by James Fast and Brian Eng of Jefferson Lab. Revised models are in development that will allow the user to specify the size of sensors being used, and the number and dimensions of the staves.

As with other central detector components, the origin of this component is at its center and its position along the beamline is adjusted using the *offset* parameter.

### **Component Options**

The following options are available for configuring this component.

| -                     |   |
|-----------------------|---|
| X, Y, Z               | Position of the object's origin relative to the red, green and blue axes respectively.  |
| Detector<br>Length    | Total length of the detector along the beam line.   |
| Bore                  | Radius from the origin to the inside of the detector (this is an advisory value and is currently used only for computing volume). |
| Radius                | Radius from the origin to the outside of the detector.  |
| Offset from<br>Center | Distance along the beamline that the detector's origin is offset from the interaction point. (HD is negative and LD is positive)  |
| Volume                | Volume in cubic meters of the detector (read-<br>only, computed as cylinders).  |

All component dimensions are specified as centimeters unless otherwise stated.

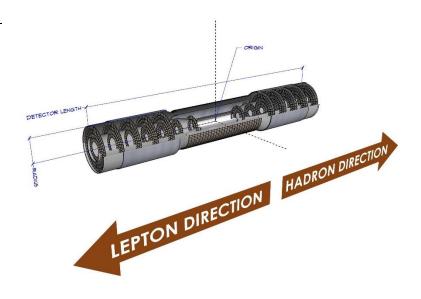


Figure 15: Silicon Detector

## **Methods for Weight Estimation**

A preliminary weight estimation can be derived by using the dimensions and materials shown in the design from Fast and Eng. In this model, the cylindrical volume of the detector is 0.30 m³. The volume of the detector that is represented by copper conductor and tubing is 0.002433 m³, the volume represented by aluminum is 0.0001573, and the volume represented by silicon is 0.002390 m³. The balance of the volume is considered to be inert gas. Using the standard densities of copper, aluminum and silicon, the formula for computing the weight of the silicon detector is given as follows:

weight = volume \* 92.31



## **IP-6 Detector Chamber**

#### Overview

The IP-6 detector chamber is the vacuum beam pipe that runs through the center of the detector. The detector chamber has a beryllium section at its center, where the hadron and lepton beam pipes converge.

The design of this component continues to evolve, as the placement of flanges and connectors are entirely dependent on the configuration of the other detector components.

## **Component Options**

The following options are available for configuring this component.

X, Y, Z Position of the object's origin relative to the red, green and blue axes respectively.

All component dimensions are specified as centimeters unless otherwise stated.

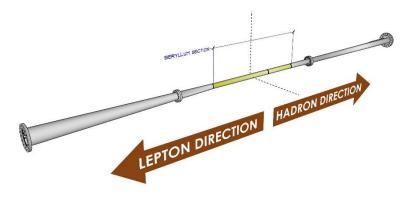


Figure 16: IP-6 Detector Chamber

## **Methods for Weight Estimation**

The design of the detector chamber is preliminary and a parametric formula for weight estimation has not been developed.

## **LEPTON DIRECTION COMPONENTS**



## **Lepton Direction Hadron Calorimeter Endcap**

#### Overview

The lepton direction endcap is the first of the components on the outgoing lepton side of the detector. Unlike components in the center of the detector, the origin of lepton direction components are at the center of the inner most face of the object, as shown in the figure at right.

As with other components, the object's origin is placed at the interaction point, and then its position is adjusted along the beamline using the offset parameter. Negative offset values move the object in the hadron direction and positive values move it in the lepton direction.

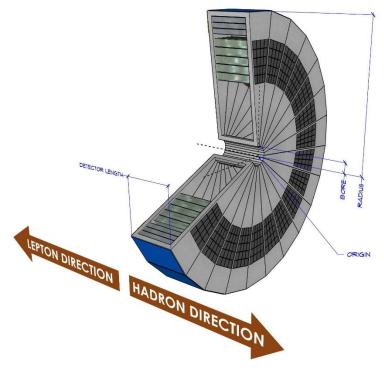


Figure 17: LD Hadron Calorimeter Endcap

## **Component Options**

The following options are available for configuring this component.

| X, Y, Z               | Position of the object's origin relative to the red, green and blue axes respectively.   |
|-----------------------|--|
| Detector<br>Length    | Total length of the detector along the beam line.  |
| Bore                  | Radius from the origin to the inside of the detector.  |
| Radius                | Radius from the origin to the outside of the detector.   |
| Offset from<br>Center | Distance along the beamline that the detector's origin is offset from the interaction point. (HD is negative and LD is positive) |
| Volume                | Volume in cubic meters of the detector (read-<br>only, computed as cylinders).   |

All component dimensions are specified as centimeters unless otherwise stated.

## **Methods for Weight Estimation**

Weight estimates for this object are also based on the CMS HB Hadron Calorimeter as described earlier. Using this approach, the weight can be calculated by applying a density coefficient to the volume, such that:

weight = volume \* 7002.3

where volume is given in cubic meters and the density is provided as  $kg/m^3$ .

See the section describing the *one-part barrel hadron calorimeter* for details.



## **Lepton Direction Electromagnetic Calorimeter**

#### Overview

Because the configuration of the electromagnetic calorimeter can vary significantly depending on factors such as the orientation of the DIRC, several versions of this dynamic component are provided. The following three versions are based on a design produced by Joshua Crafts and has several configurable parameters.

The radius parameter represents the external radius at the perimeter of the outer blocks. Supporting structure for the glass blocks extends an additional ~12% beyond the specified radius. Structural members extend from glass supports to the perimeter specified by the support radius parameter. These members allow the electromagnetic calorimeters weight to be transferred to an external structure, such as the barrel hadron calorimeter.

The bore radius and inner block radius are automatically calculated based on the calorimeter's distance from the origin. The bore is at a 4.5 degree radius from the origin and the inner blocks are at a 15 degree radius from the origin. The inner block count and outer block count parameter contain an estimate of the number of glass blocks that will fit within each of the volumes.

As with other lepton direction components, the origin is positioned at the center of the inner face and the offset is used to position the object along the beamline.

### **Component Options**

The following options are available for configuring this component.

| X, Y, Z              | Position of the object's origin relative to the red, green and blue axes respectively. |
|----------------------|--|
| Inner Block<br>Count | Estimated number of 2x2 cm blocks that will fit in the interior radial volume.         |
| Outer Block<br>Count | Estimated number of 4x4 cm blocks that will fit in the exterior radial volume.         |
| Detector<br>Length   | Total length of the detector along the beam line.                                      |

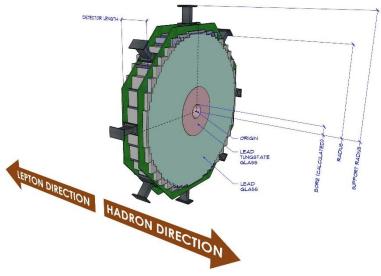


Figure 18: LD Electromagnetic Calorimeter

| Bore                  | Computed radius from the origin to the inside of the detector (4.5 degree radius from the origin / read-only).                   |
|-----------------------|--|
| Radius                | Radius from the origin to the outside of the detector.   |
| Support<br>Radius     | Radius from the origin to the supporting structure to which this assembly attaches.  |
| Offset from<br>Center | Distance along the beamline that the detector's origin is offset from the interaction point. (HD is negative and LD is positive) |
| Volume                | Volume in cubic meters of the detector (read-<br>only, computed as cylinders).   |

All component dimensions are specified as centimeters unless otherwise stated.

## **Methods for Weight Estimation**

The volume parameter of this detector includes the volume of the lead glass and the support structure. A weight estimate for this object can be generated by multiplying the volume of the glass by the density of lead glass and the balance of the volume by the density of steel. For a more precise calculation, the user may independently compute the volumes of lead glass and lead tungstate glass, as their density differs. A simple weight estimate is given by:



## **Lepton Direction Electromagnetic Calorimeter (PWO)**

#### Overview

This version of the electromagnetic calorimeter is designed to fit within the bore of the DIRC and it consists entirely of lead tungstate glass. As with the previous electromagnetic calorimeter, it has a radius parameter which specifies the radius to the perimeter of the lead tungstate glass, and a support radius which represents the distance from the center to the bore of the external supporting component.

In order to make this component fit properly with the component that is supporting it, the number of support sides may be specified. The size of the bore is based on the component's distance from the interaction point and is at a 4.5 degree radius from the origin. The number of blocks is the estimated number of 2x2cm blocks that will fit within the glass surface of the detector.

## **Component Options**

The following options are available for configuring this component.

| X, Y, Z       | Position of the object's origin relative to the red, green and blue axes respectively.                         |
|---------------|--|
| Block Count   | Estimated number of 2x2 cm blocks that will fit in the detector's radial volume.                               |
| Detector      | Total length of the detector along the beam  |
| Length        | line.  |
| Bore          | Computed radius from the origin to the inside of the detector (4.5 degree radius from the origin / read-only). |
| Radius        | Radius from the origin to the outside of the detector.   |
| Support Sides | Number of sides on the supporting structure (typically matches the number of sides on the parent detector).    |

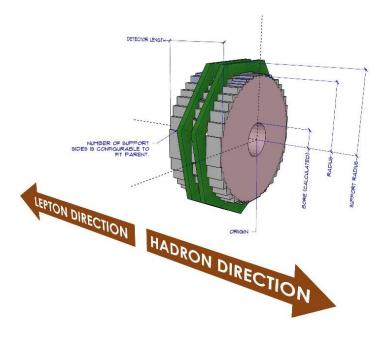


Figure 19: LD Electromagnetic Calorimeter (PWO)

| Support<br>Radius     | Radius from the origin to the supporting structure to which this assembly attaches (typically, the parent's bore radius).        |
|-----------------------|--|
| Offset from<br>Center | Distance along the beamline that the detector's origin is offset from the interaction point. (HD is negative and LD is positive) |
| Volume                | Volume in cubic meters of the detector (read-<br>only, computed as cylinders).   |

All component dimensions are specified as centimeters unless otherwise stated.

### **Methods for Weight Estimation**

The method for estimating weight for this object is similar to that used for the previous electromagnetic calorimeter, except that the density of lead tungstate glass is used for the entire glass volume. Therefore:



## **Lepton Direction Electromagnetic Calorimeter (Compact)**

#### Overview

This compact electromagnetic calorimeter is also designed to fit within the bore of the DIRC detector. In this case, the calorimeter consists of both lead glass and lead tungstate blocks. The radius parameter specifies the outer most perimeter of glass on the detector. The size of the bore and the perimeter of the lead tungstate glass are computed based on the object's distance from the origin. The number of blocks that will fit within both the inner and outer glass perimeters are calculated based on the glass volumes.

The *support radius* specifies the distance from the center to the bore of the supporting structure. Since the number of DIRC segments may vary, the *support sides* parameter allows the user to specify the number of sides on the electromagnetic calorimeter so that it matches the DIRC.

## **Component Options**

The following options are available for configuring this component.

| X, Y, Z              | Position of the object's origin relative to the red, green and blue axes respectively.                         |
|----------------------|--|
| Inner Block<br>Count | Estimated number of 2x2 cm blocks that will fit in the interior radial volume.                                 |
| Outer Block<br>Count | Estimated number of 4x4 cm blocks that will fit in the exterior radial volume.                                 |
| Detector<br>Length   | Total length of the detector along the beam line.  |
| Bore                 | Computed radius from the origin to the inside of the detector (4.5 degree radius from the origin / read-only). |
| Radius               | Radius from the origin to the outside of the detector.   |
| Support Sides        | Number of sides on the supporting structure (typically matches the number of sides on the parent detector).    |

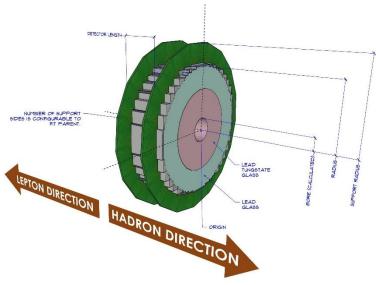


Figure 20: LD Electromagnetic Calorimeter (Compact)

| Support<br>Radius     | Radius from the origin to the supporting structure to which this assembly attaches (typically, the parent's bore radius).        |
|-----------------------|--|
| Offset from<br>Center | Distance along the beamline that the detector's origin is offset from the interaction point. (HD is negative and LD is positive) |
| Volume                | Volume in cubic meters of the detector (read-<br>only, computed as cylinders).   |

All component dimensions are specified as centimeters unless otherwise stated.

## **Methods for Weight Estimation**

The volume parameter of this detector includes the volume of the lead glass and the support structure. A weight estimate for this object can be generated by multiplying the volume of the glass by the density of lead glass and the balance of the volume by the density of steel. For a more precise calculation, the user may independently compute the volumes of lead glass and lead tungstate glass, as their density differs. A simple weight estimate is given by:

$$glass = ((PI * radius^2)-(PI * bore^2))*length$$
  
 $steel = volume - glass$   
 $weight = glass*6220 kg/m^3 + steel*7850 kg/m^3$ 



## **Lepton Direction Time of Flight Detector**

#### Overview

The LD time of flight detector uses the standard set of parameters that are available in the other detector components. As a lepton direction component, its origin is positioned at the center of the inside face as shown in the figure at right.

As with other components, the object's origin is placed at the interaction point, and then its position is adjusted along the beamline using the *offset* parameter. Negative offset values move the object in the hadron direction and positive values move it in the lepton direction.

## **Component Options**

The following options are available for configuring this component.

| X, Y, Z     | Position of the object's origin relative to the red, green and blue axes respectively. |
|-------------|--|
| Detector    | Total length of the detector along the beam  |
| Length      | line.  |
| Bore        | Radius from the origin to the inside of the detector.                                  |
| Radius      | Radius from the origin to the outside of the detector.                                 |
| Offset from | Distance along the beamline that the   |
| Center      | detector's origin is offset from the interaction                                       |
| Center      | point. (HD is negative and LD is positive)   |
| Volume      | Volume in cubic meters of the detector (read-  |
|             | only, computed as cylinders).  |

All component dimensions are specified as centimeters unless otherwise stated.

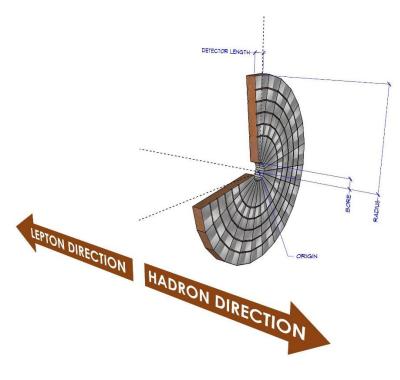


Figure 21: LD Time of Flight

## **Methods for Weight Estimation**

A parametric approach for weight estimation has been developed based on the PANDA forward time of flight detector (PANDA Collaboration, 2018). The weight of the PANDA detector together with the supporting frame, the wheels and the rail is estimated to be 800 kg, and it has a volume of 1,320,000 cm<sup>3</sup>. Therefore, using the volume parameter of the dynamic component, the weight can be estimated as follows:

weight = volume \* 606.1



## **Lepton Direction Cherenkov Counter**

#### Overview

The LD cherenkov counter uses the standard set of parameters that are available in the other detector components. As a lepton direction component, its origin is positioned at the center of the inside face as shown in the figure at right.

As with other components, the object's origin is placed at the interaction point, and then its position is adjusted along the beamline using the *offset* parameter. Negative offset values move the object in the hadron direction and positive values move it in the lepton direction.

### **Component Options**

The following options are available for configuring this component.

| X, Y, Z               | Position of the object's origin relative to the red, green and blue axes respectively.   |
|-----------------------|--|
| Detector<br>Length    | Total length of the detector along the beam line.  |
| Bore                  | Radius from the origin to the inside of the detector.  |
| Radius                | Radius from the origin to the outside of the detector.   |
| Offset from<br>Center | Distance along the beamline that the detector's origin is offset from the interaction point. (HD is negative and LD is positive) |
| Volume                | Volume in cubic meters of the detector (read-<br>only, computed as cylinders).   |

All component dimensions are specified as centimeters unless otherwise stated.

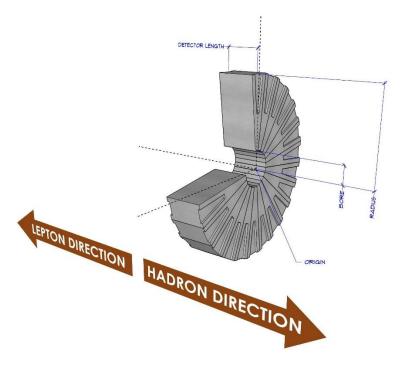


Figure 22: LD Cherenkov Counter

## Methods for Weight Estimation

The weight of the RICH detector can be estimated using the parameters from the CLAS12 RICH detector (CLAS Collaboration, 2013). As noted in their technical design report, each RICH sector weighs 1300 kg, and the modeled volume of a RICH sector is 7.011 m<sup>3</sup>. This allows the volume to be used to compute the weight as follows:

weight = volume \* 185.42



## **Lepton Direction Micro-Pattern Gas Detector**

#### Overview

The LD micro-pattern gas detector uses the standard set of parameters that are available in the other detector components. As a lepton direction component, its origin is positioned at the center of the inside face as shown in the figure at right.

As with other components, the object's origin is placed at the interaction point, and then its position is adjusted along the beamline using the *offset* parameter. Negative offset values move the object in the hadron direction and positive values move it in the lepton direction.

### **Component Options**

The following options are available for configuring this component.

| X, Y, Z               | Position of the object's origin relative to the red, green and blue axes respectively.   |
|-----------------------|--|
| Detector<br>Length    | Total length of the detector along the beam line.  |
| Bore                  | Radius from the origin to the inside of the detector.  |
| Radius                | Radius from the origin to the outside of the detector.   |
| Offset from<br>Center | Distance along the beamline that the detector's origin is offset from the interaction point. (HD is negative and LD is positive) |
| Volume                | Volume in cubic meters of the detector (read-<br>only, computed as cylinders).   |

All component dimensions are specified as centimeters unless otherwise stated.

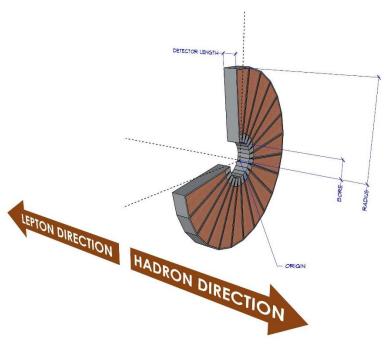


Figure 23: LD Micro-Pattern Gas Detector

## **Methods for Weight Estimation**

The weight of the micro-pattern gas detector may be estimated based on the parameters from the Super BigBite GEM trackers (Liyanage, 2013). In this design, each chamber weighed 5 kg and was 50cm x 50cm x 10cm, providing the following formula:

weight = volume \* 200

## HADRON DIRECTION COMPONENTS



## RICH (Ring Image Cherenkov) Detector

#### Overview

The RICH Detector is the first of the hadron direction detectors, however, its unusual configuration causes its origin to be at the center of the outside face. The RICH detector has a number of parameters that are not available in other detectors. Specifically, its shape is governed by three distinct radii; the aerogel radius represents the face farthest to the lepton direction, the LD radius is near the middle of the detector, and the HD radius is at the far hadron side of the detector. The length of the aerogel section and the detector section are also independently configurable.

Because the number of RICH segments that will be used has not been determined, the segment count parameter can be used to increase or decrease the number of sectors. Current guidance from Beni Zihlman of Jefferson Lab is that the RICH detector will be limited to six sectors.

Although the detector is faceted, its volume is estimated using cylindrical formulas, which should be adequate for weight calculations.

## **Component Options**

The following options are available for configuring this component.

| X, Y, Z            | Position of the object's origin relative to the red, green and blue axes respectively. |
|--------------------|--|
| Aerogel<br>Length  | Length of the aerogel section of the detector.   |
| Aerogel<br>Radius  | Radius of the <u>front</u> of the aerogel section of the detector.                     |
| Detector<br>Length | Length (along the beamline) of the detector portion of the RICH.                       |
| Bore               | Radius from the origin to the inside of the detector.                                  |
| HD Radius          | Radius from the origin to the outside of the detector on the hadron direction end.     |

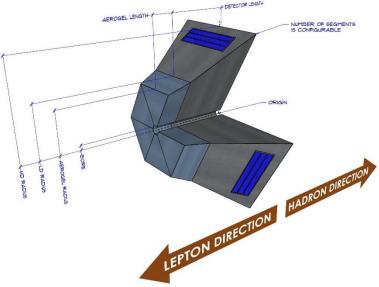


Figure 24: RICH Detector

| LD Radius             | Radius from the origin to the outside of the detector on the lepton direction end.   |
|-----------------------|--|
| Segment<br>Count      | The number of RICH segments that are installed in the detector.  |
| Offset from<br>Center | Distance along the beamline that the detector's origin is offset from the interaction point. (HD is negative and LD is positive) |
| Volume                | Volume in cubic meters of the detector (read-<br>only, computed as cylinders).   |

All component dimensions are specified as centimeters unless otherwise stated.

## **Methods for Weight Estimation**

The weight of the RICH detector can be estimated using the parameters from the CLAS12 RICH detector (CLAS Collaboration, 2013). As noted in their technical design report, each RICH sector weighs 1300 kg, and the modeled volume of a RICH sector is 7.011 m³. This allows the volume to be used to compute the weight as follows:

weight = volume \* 185.42



## **Hadron Direction Hadron Calorimeter Endcap**

#### Overview

The hadron direction endcap is the outer most component on the outgoing lepton side of the detector. Unlike components in the center of the detector, the origin of hadron direction components are at the center of the inner most face of the object, as shown in the figure at right.

As with other components, the object's origin is placed at the interaction point, and then its position is adjusted along the beamline using the *offset* parameter. Negative offset values move the object in the hadron direction and positive values move it in the lepton direction.

### **Component Options**

The following options are available for configuring this component.

| X, Y, Z               | Position of the object's origin relative to the red, green and blue axes respectively.   |
|-----------------------|--|
| Detector<br>Length    | Total length of the detector along the beam line.  |
| Bore                  | Radius from the origin to the inside of the detector.  |
| Radius                | Radius from the origin to the outside of the detector.   |
| Offset from<br>Center | Distance along the beamline that the detector's origin is offset from the interaction point. (HD is negative and LD is positive) |
| Volume                | Volume in cubic meters of the detector (read-<br>only, computed as cylinders).   |

All component dimensions are specified as centimeters unless otherwise stated.

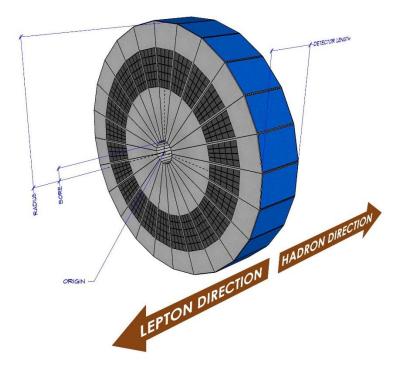


Figure 25: HD Hadron Calorimeter Endcap

### **Methods for Weight Estimation**

Weight estimates for this object are also based on the CMS HB Hadron Calorimeter as described earlier. Using this approach, the weight can be calculated by applying a density coefficient to the volume, such that:

weight = 7002.3 \* volume

where volume is given in cubic meters and the density is provided as  $kq/m^3$ .

See the section describing the **one-part barrel hadron calorimeter** for details.



## **Hadron Direction Electromagnetic Calorimeter**

#### Overview

Unlike the lepton direction electromagnetic calorimeter, this component is a more primitive placeholder that will be enhanced in future versions. This object scales proportionately with changes in the radius and length, meaning that the visual size of the bore may not be consistent with its actual size. For computational purposes (and to accommodate future versions) a bore parameter is provided and is used for calculating the component's volume.

The origin of this component is at the center of the inside face. As with other components, this object should be centered at the origin and positioned along the beamline using the *offset* parameter.

## **Component Options**

The following options are available for configuring this component.

| X, Y, Z               | Position of the object's origin relative to the red, green and blue axes respectively.  |
|-----------------------|---|
| Detector<br>Length    | Total length of the detector along the beam line.   |
| Bore                  | Radius from the origin to the inside of the detector (this is an advisory value and is currently used only for computing volume). |
| Radius                | Radius from the origin to the outside of the detector.  |
| Offset from<br>Center | Distance along the beamline that the detector's origin is offset from the interaction point. (HD is negative and LD is positive)  |
| Volume                | Volume in cubic meters of the detector (read-<br>only, computed as cylinders).  |

All component dimensions are specified as centimeters unless otherwise stated.

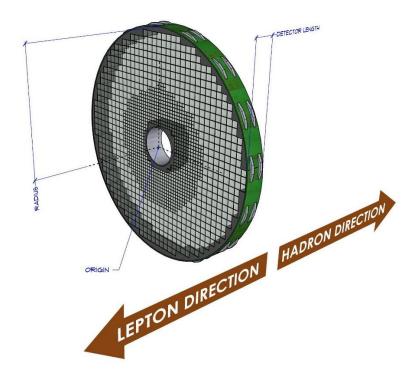


Figure 26: HD Electromagnetic Calorimeter

## **Methods for Weight Estimation**

Because the design of this electromagnetic calorimeter is not fully defined, its weight is estimated as the product of its computed volume and the density of lead glass. This provides the following formula:

weight = volume \* 6220



## **Hadron Direction Time of Flight Detector**

#### Overview

The HD time of flight detector uses the standard set of parameters that are available in the other detector components. As a hadron direction component, its origin is positioned at the center of the inside face as shown in the figure at right.

As with other components, the object's origin is placed at the interaction point, and then its position is adjusted along the beamline using the *offset* parameter. Negative offset values move the object in the hadron direction and positive values move it in the lepton direction.

### **Component Options**

The following options are available for configuring this component.

| X, Y, Z               | Position of the object's origin relative to the red, green and blue axes respectively.   |
|-----------------------|--|
| Detector<br>Length    | Total length of the detector along the beam line.  |
| Bore                  | Radius from the origin to the inside of the detector.  |
| Radius                | Radius from the origin to the outside of the detector.   |
| Offset from<br>Center | Distance along the beamline that the detector's origin is offset from the interaction point. (HD is negative and LD is positive) |
| Volume                | Volume in cubic meters of the detector (read-<br>only, computed as cylinders).   |

All component dimensions are specified as centimeters unless otherwise stated.

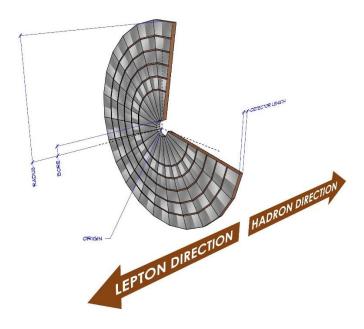


Figure 27: HD Time of Flight Detector

## **Methods for Weight Estimation**

A parametric approach for weight estimation has been developed based on the PANDA forward time of flight detector (PANDA Collaboration, 2018). The weight of the PANDA detector together with the supporting frame, the wheels and the rail is estimated to be 800 kg, and it has a volume of 1,320,000 cm<sup>3</sup>. Therefore, using the volume parameter of the dynamic component, the weight can be estimated as follows:

weight = volume \* 606.1



## **Hadron Direction Transition Radiation Detector**

#### Overview

The HD transition radiation detector uses the standard set of parameters that are available in the other detector components. As a hadron direction component, its origin is positioned at the center of the inside face as shown in the figure at right.

As with other components, the object's origin is placed at the interaction point, and then its position is adjusted along the beamline using the *offset* parameter. Negative offset values move the object in the hadron direction and positive values move it in the lepton direction.

### **Component Options**

The following options are available for configuring this component.

| X, Y, Z               | Position of the object's origin relative to the red, green and blue axes respectively.   |
|-----------------------|--|
| Detector<br>Length    | Total length of the detector along the beam line.  |
| Bore                  | Radius from the origin to the inside of the detector.  |
| Radius                | Radius from the origin to the outside of the detector.   |
| Offset from<br>Center | Distance along the beamline that the detector's origin is offset from the interaction point. (HD is negative and LD is positive) |
| Volume                | Volume in cubic meters of the detector (read-<br>only, computed as cylinders).   |

All component dimensions are specified as centimeters unless otherwise stated.

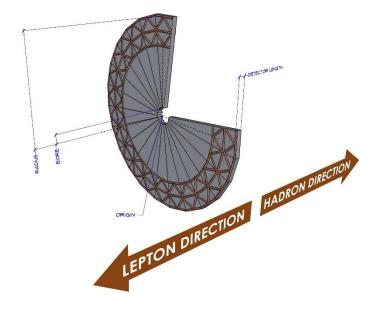


Figure 28: HD Transition Radiation Detector

## **Methods for Weight Estimation**

The weight of the transition radiation detector may be estimated using the parameters from the ALICE transition radiation detector (ALICE Collaboration, 2018) (Mercado, 2004). The ALICE TRD consists of 18 supermodules, weighing 1.65 tons (1497 kg) each. The modeled volume of the complete ALICE TRD is 112.62 m³, which yields the following formula.

weight = volume \* 239.3



## **Hadron Direction Micro-Pattern Gas Detector**

#### Overview

The HD transition radiation detector uses the standard set of parameters that are available in the other detector components. As a hadron direction component, its origin is positioned at the center of the inside face as shown in the figure at right.

As with other components, the object's origin is placed at the interaction point, and then its position is adjusted along the beamline using the *offset* parameter. Negative offset values move the object in the hadron direction and positive values move it in the lepton direction.

### **Component Options**

The following options are available for configuring this component.

| X, Y, Z               | Position of the object's origin relative to the red, green and blue axes respectively.   |
|-----------------------|--|
| Detector<br>Length    | Total length of the detector along the beam line.  |
| Bore                  | Radius from the origin to the inside of the detector.  |
| Radius                | Radius from the origin to the outside of the detector.   |
| Offset from<br>Center | Distance along the beamline that the detector's origin is offset from the interaction point. (HD is negative and LD is positive) |
| Volume                | Volume in cubic meters of the detector (read-only, computed as cylinders).   |

All component dimensions are specified as centimeters unless otherwise stated.

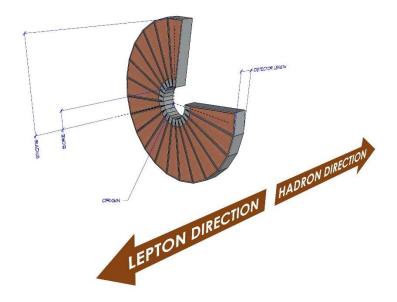


Figure 29: HD Micro-Pattern Gas Detector

## **EXTERNAL COMPONENTS AND SYSTEMS**



## **Accelerator Superconducting Magnet Body**

#### Overview

The accelerator superconducting magnet body component is used to create preliminary models that show the placement of beamline magnets outside of the detector. This particular component may be used in conjunction with the accelerator superconducting magnet to illustrate a larger cryostat that contains multiple accelerator magnets.

The magnet body is significantly simpler than most components and its primary attributes are limited to length and radius. For positioning purposes, the component also has an option that allows the user to specify the distance from the floor to the center of the magnet. This becomes pertinent when it is combined with the accelerator SC magnet, which uses the "floor to center" attribute to draw the support structure.

Unlike other objects, this component's origin is the center of the magnet. The Y parameter is altered to move it along the beamline.

### **Component Options**

The following options are available for configuring this component.

| X, Y, Z            | Position of the object's origin relative to the red, green and blue axes respectively. |
|--------------------|--|
| Magnet<br>Length   | Total length of the magnet along the beam line.  |
| Radius             | Radius from the origin to the outside of the magnet.                                   |
| Floor to<br>Center | Distance from an arbitrarily located floor to the center of the magnet.                |

All component dimensions are specified as centimeters unless otherwise stated.

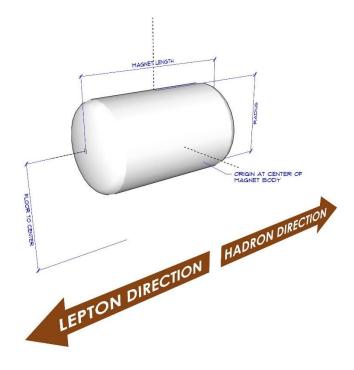


Figure 30: Accelerator Superconducting Magnet Body

## **Methods for Weight Estimation**

Because this component is permanently affixed and is not relocated as part of the detector package, a weight estimation formula is not provided.



## **Accelerator Superconducting Magnet**

#### Overview

The accelerator superconducting magnet component is similar to the magnet body described earlier, with some supplemental features. This component has an extensible base that expands and lengthens as the size of the magnet is altered. For compound magnets (those with multiple magnets within a single cryostat), this object can be combined with two or more embedded magnet bodies to produce a visualization.

The magnet body is significantly simpler than most components and its primary attributes are limited to length and radius. For positioning purposes, the component also has an option that allows the user to specify the distance from the floor to the center of the magnet. This attribute is used to draw the support structure.

Unlike other objects, this component's origin is the center of the magnet. The Y parameter is altered to move it along the beamline.

## **Component Options**

The following options are available for configuring this component.

| X, Y, Z            | Position of the object's origin relative to the red, green and blue axes respectively. |
|--------------------|--|
| Magnet<br>Length   | Total length of the magnet along the beam line.  |
| Radius             | Radius from the origin to the outside of the magnet.                                   |
| Floor to<br>Center | Distance from an arbitrarily located floor to the center of the magnet.                |

All component dimensions are specified as centimeters unless otherwise stated.

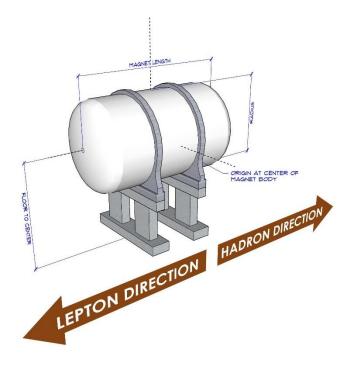


Figure 31: Accelerator Superconducting Magnet

### **Methods for Weight Estimation**

Because this component is permanently affixed and is not relocated as part of the detector package, a weight estimation formula is not provided.



## **IP-8 Muon Shield**

### Overview

The IP-8 muon shield component represents the muon shields that are currently installed in the IP-8 experimental hall. Prior to installing the new detector, these shields will need to be removed or altered to facilitate the new system.

Because this is a static system, it has very few user configurable options.

## **Component Options**

The following options are available for configuring this component.

X, Y, Z
Position of the object's origin relative to the red, green and blue axes respectively.

All component dimensions are specified as centimeters unless otherwise stated.



Figure 32: Accelerator Superconducting Magnet Body

## **Methods for Weight Estimation**

The muon chambers are made of iron and have a modeled volume of 276 cubic meters and have a total estimated weight of 2,172,948 kilograms.

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